

Complexité avancée - TD 3

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We recall the space-hierarchy theorem.

Theorem 1 (Space-hierarchy theorem). *For two space-constructible functions f and g such that $f = o(g)$, we have $\text{DSPACE}(f) \subsetneq \text{DSPACE}(g)$.*

Exercise 1 (Poly-logarithmic space). 1. Let $\text{polyL} = \cup_{k \in \mathbb{N}} \text{SPACE}(\log^k)$. Show that polyL does not have a complete problem for logarithmic space reduction.¹

2. Recall that $\text{PSPACE} = \cup_{k \in \mathbb{N}} \text{SPACE}(n^k)$. Does PSPACE have a complete problem for logarithmic space reduction? Why doesn't the proof of the previous question apply to PSPACE ?

Solution 1. 1. Assume towards a contradiction that there exists a polyL -complete problem L for logspace reduction. Then, there exists $k \in \mathbb{N}$ such that $L \in \text{SPACE}(\log^k)$. Let us show that $\text{SPACE}(\log^k) = \text{SPACE}(\log^{k+1})$, which is a contradiction with the space hierarchy theorem. Let $L' \in \text{SPACE}(\log^{k+1}) \subseteq \text{polyL}$. There exists a reduction f of L' to L that can be computed in logarithmic space since L is polyL -complete. Now, consider a Turing machine that, on an input w , computes $f(w)$ in logarithmic space and then simulates a Turing machine deciding L that runs in space \log^k on $f(w)$. Note that here, it is important not store $f(w)$ on a working tape as this could make the space used exceed the \log^k space bound. Instead, one must use a virtual tape where we only compute bits of $f(w)$ when they are needed without remembering the whole computation. Then, note that $|f(w)| = O(|w|^c)$ for some $c \geq 0$. Hence, the space used to check if $f(w)$ is in L is lower than $\log^k(|f(w)|)$ hence is in $c^k \cdot \log^k(O(|w|)) = O(\log^k(|w|))$. We conclude with the speed-up theorem to get that $L' \in \text{SPACE}(\log^k)$. We get $\text{SPACE}(\log^k) = \text{SPACE}(\log^{k+1})$ which is in contradiction with the space hierarchy theorem. Hence L cannot exist.

2. PSPACE does have complete problems for logarithmic space reductions (such as TQBF). However, if we try to apply the previous proof to establish that $\text{SPACE}(n^k) = \text{SPACE}(n^{k+1})$, a problem arises: since $|f(w)|$ is in $O(|w|^c)$, we have $|f(w)|^k$ in $O(|w|^{c \cdot k}) \neq O(|w|^k)$ if $c > 1$.

Exercise 2 (Padding argument). 1. Show that if $\text{DSPACE}(n^c) \subseteq \text{NP}$ for some $c > 0$, then $\text{PSPACE} \subseteq \text{NP}$.

Hint: for $L \in \text{DSPACE}(n^c)$ one may consider the language $\tilde{L} = \{(x, w_x) \mid x \in L\}$, where w_x is a word written in unary.

2. Deduce that $\text{DSPACE}(n^c) \neq \text{NP}$.

¹Note that, from this, we can deduce that $\text{polyL} \neq \text{P}$.

Solution 2. 1. Assume $\text{DSPACE}(n^c) \subseteq \text{NP}$ and consider any $L \in \text{PSPACE}$: we have to prove $L \in \text{NP}$. For some k , we have $L \in \text{DSPACE}(n^k)$. Let M be a Turing Machine deciding L in space n^k . Now, consider the language $\tilde{L} = \{(x, 1^{\lfloor |x|^{k/c} \rfloor}) \mid x \in L\}$ and consider the Turing machine \tilde{M} that, on an input w , checks that it has the form $w = (x, 1^\ell)$, verifies that $\ell = \lfloor |x|^{k/c} \rfloor$, and if so launches a simulation of M on x . Note that computing $\lfloor |x|^{k/c} \rfloor$ only uses k/c nested loops going from 1 to $|x|$, which can be done in logspace since k/c is a “constant” that depends on M , not x . Then, \tilde{M} accepts \tilde{L} and the space used by \tilde{M} is in $|x|^k = \lfloor |x|^{k/c} \rfloor^c \leq |w|^c$. Hence, $\tilde{L} \in \text{DSPACE}(n^c) \subseteq \text{NP}$. Thus $\tilde{L} \in \text{NP}$. As we can reduce L to \tilde{L} by transforming x into $(x, 1^{\lfloor |x|^{k/c} \rfloor})$ in logspace, we do have that $L \in \text{NP}$.

2. Assume $\text{DSPACE}(n^c) = \text{NP}$, then $\text{DSPACE}(n^{c+1}) \subseteq \text{PSPACE} = \text{NP} = \text{DSPACE}(n^c)$ which is in contradiction with the space hierarchy theorem.

Exercise 3 (On the existence of One-way function). A one-way function is a bijection f from k -bit integers to k -bit integers such that f is computable in polynomial time, but f^{-1} is not. Prove that for all one-way functions f , we have

$$A := \{(x, y) \mid f^{-1}(x) < y\} \in (\text{NP} \cap \text{coNP}) \setminus \text{P}$$

Solution 3. 1. $A \in \text{NP}$: consider a Turing machine that, on an input $w = (x, y)$, guesses a number c (with $|c| = |x|$) and checks in polynomial time that $f(c) = x$ and $c < y$. This non-deterministic TM runs in polynomial time and accepts the language A .

2. $A \in \text{coNP} \Leftrightarrow \{(x, y) \mid f^{-1}(x) \geq y\} \in \text{NP}$, which we solve as previously.

3. Assume that $A \in \text{P}$. Then we build a Turing machine running in polynomial time that computes f^{-1} : On an input x such that $|x| = n$, there is 2^n possibility for the value of $f^{-1}(x)$. We consider a TM that proceeds by a binary search on the possible values v of $f^{-1}(x)$ until it finds some v with $(x, v-1) \in A$ and $(x, v) \notin A$ and deduce $f^{-1}(x) = v - 1$. Since at most n tests are necessary and each test is polynomial time, this TM runs in polynomial time.

Exercise 4 (Regular languages). Let REG denote the set regular/rational languages.

1. Show that for all $L \in \text{REG}$, L is recognized by a TM running in space 0 and time $n + 1$.²

2. Exhibit a language recognized by a TM running in space $\log n$ and time $O(n)$ that is not in REG .

Solution 4. 1. Consider $L \in \text{REG}$. It is recognized by a finite automaton \mathcal{A} . We consider the TM with the same states than \mathcal{A} that, on an input w , simulates the execution of w on \mathcal{A} and accepts if \mathcal{A} does. This TM does not consumes any space and runs in time $n + 1$ (the $n + 1$ -th step reads the first blank after the input and accepts/rejects).

2. The language $L = \{a^n \cdot b^n \mid n \geq 0\}$ is not regular and can be recognized by a TM that counts the number of a with a binary counter, decrements it for each b seen and accepts if, at the end of the word, the counter equal 0.

²In fact, regular languages exactly correspond to languages that can be recognized in such a way.

Exercise 5 (Yet another NL-complete problem). For a finite set X , a subset $S \subseteq X$, and a binary operation $* : X \times X \rightarrow X$ defined on X , we inductively define $S_{0,*} := S$ and $S_{i+1,*} := S_{i,*} \cup \{x * y \mid x, y \in S_{i,*}\}$. The closure of S with regard to $*$ is the set $S_* = \bigcup_{i \in \mathbb{N}} S_{i,*}$.

Show that the following problem AGEN is NL-complete.

- *Input:* A finite set X , a binary operation $* : X \times X \rightarrow X$ that is associative (i.e. $(x * y) * z = x * (y * z)$ for all $x, y, z \in X$), a subset $S \subseteq X$ and a target $t \in X$.
- *Output:* Yes if and only if $t \in S_*$.

Solution 5. 1. First, it has to be noted that the predicate: $*$ is associative can be checked in logspace (as it only amounts to loop on all triples of X and check the table describing $*$).

2. AGEN is in NL: Consider a subset $S \subseteq X$ and an associative law $* : X \times X \rightarrow X$. Note that, we have $t \in S_*$ if and only if $t = x_1 * \dots * x_n$ for some $x_1, \dots, x_n \in S$. Since $*$ is associative, the parentheses do not matter. We denote by $x_{\leq i}$ the word $x_{\leq i} := x_1 \dots x_i$. For the shortest such sequence generating t , we have that all $x_{\leq i}$ are distinct. It follows that we can guess the sequence of x_i while only keeping a pointer on the current element $x_{\leq i}$, with the sequence being of size at most $|X|$.

3. We reduce from Path. Consider a directed graph $G = (V, E)$ and $s, t \in V$. We let $X := V \cup V \times V \cup \{\perp\}$ and $S := E \cup \{s\}$. We then define the law $* : X \times X \rightarrow X$ in the following way (every possibility that is not displayed here induces \perp):

- For all $e, e' \in V$, $e * (e, e') := e'$;
- For all $e, e', f \in V$, $(e, e') * (e', f) := (e, f)$.

One can check that this law is associative, that t is reachable from s if and only if t can be generated from S and that this reduction can be computed in logspace.

Exercise 6 (Solving reachability games). A two player (turn-based) game is a directed graph $G = (V, E)$ where the set of vertices $V = V_A \uplus V_B$ is partitioned into vertices belonging to Player A (i.e. V_A) and vertices belonging to Player B (i.e. V_B) with a distinguished vertex $v_0 \in V$ that is the starting vertex. The graph is non-blocking in the sense that every vertex has a successor, i.e. $\text{Succ}(v) = \{v' \in V \mid (v, v') \in E\} \neq \emptyset$ for all $v \in V$. A play then corresponds to a finite or infinite path $\rho = v_0 \cdot v_1 \dots \in V^* \cdot V^\omega$ with v_0 is the starting vertex. If the play is at a node $v_i \in V_A$ then it is Player A's turn to choose the next vertex $v_{i+1} \in \text{Succ}(v_i)$, it is Player B's turn if $v_i \in V_B$. A winning condition sets when a play is winning for Player A (we consider win/lose games, hence if Player A does not win, Player B does). A Player $C \in \{A, B\}$ has a winning strategy (or wins) from a vertex $v \in V$ if she can choose the next move in all vertices in V_C such that she wins in any play that starts in v .

1. Assume that the winning condition is a reachability objective: given a target set of states $T \subseteq V$, Player A wins if and only if a state in T is seen at some point. Show that deciding the winner of a reachability game from the vertex $v_0 \in V$ can be done in polynomial time.

Hint: construct inductively the set of states from which Player A can ensure to get closer to the target T (that is called the attractor of the set T).

2. Consider some $k \in \mathbb{N}$. A k -generalized reachability condition is the following: given k target sets of states $T_1, \dots, T_k \subseteq V$, Player A wins if and only if, for all $1 \leq i \leq k$, a state in T_i is seen at some point. Show that deciding the winner of a k -generalized reachability game from the vertex $v_0 \in V$ can be done in polynomial time.

Solution 6. 1. Consider a reachability game $G = (V, E)$ and $T \subseteq V$. Let us define inductively the sequence of sets of states $(X_i)_{i \in \mathbb{N}} \subseteq V^{\mathbb{N}}$ with $X_0 := T$ and, for all $i \geq 0$, we have:

$$X_{i+1} := X_i \cup \{v \in V_A \mid \text{Succ}(v) \cap X_i \neq \emptyset\} \cup \{v \in V_B \mid \text{Succ}(v) \subseteq X_i\}$$

Finally, let $X := \bigcup_{i \in \mathbb{N}} X_i \subseteq V$. Then, we claim that Player A wins (i.e. has a winning strategy) if and only if $v_0 \in X$.

First, for all $x \in X$, we denote by $i(x)$ the smallest index $i \in \mathbb{N}$ such that $x \in X_i$. That is, $i(x) := \min\{i \in \mathbb{N} \mid x \in X_i\}$. Assume that Player A chooses her move so that, for all $v \in X \cap V_A$ with $i(v) > 0$, the successor chosen $v' \in V$ is so that $v' \in X$ and $i(v') < i(v)$ (which is possible by definition of X). Note that, by definition of X and i , for all $v \in X \cap V_B$ such that $i(v) > 0$, we have $\text{Succ}(v) \subseteq \{v' \in X \mid i(v') < i(v)\}$. Now, any play $\rho = x_0 \cdot x_1 \cdots$ starting in a vertex $v \in X$ ensures $i(x_0) > i(x_1) > \cdots$ until a vertex $x_i \in X$ is so that $i(x_i) = 0$. That is, $x_i \in X_0 = T$. It follows that Player A wins from any vertex in X .

Similarly, let us show that Player B wins from any vertex not in X . Assume that Player B chooses her move so that, for all $v \in (V \setminus X) \cap V_B$, the successor chosen $v' \in V$ is so that $v' \in V \setminus X$ which is possible by definition of X . Note that, for all $v \in (V \setminus X) \cap V_A$, we have $\text{Succ}(v) \subseteq (V \setminus X)$ by definition of X . Now, consider a play $\rho = x_0 \cdot x_1 \cdots$ starting at a vertex $v_0 \in V \setminus X$. We have that, for all $i \in \mathbb{N}$, if $x_i \notin X$ then $x_{i+1} \notin X$ and $v_0 \notin X$. That is, no vertex in the play ρ is in X , in particular, it never reaches T . Hence, Player B wins from any vertex not in X .

Overall, we have that Player A wins from v_0 if and only if $v_0 \in X$. Furthermore, the set X can be computed in polynomial time (as it requires at most $|V|$ loops over all states not in X). Therefore, determining the winner of a reachability game can be done in polynomial time.

2. We reduce to the previous problem. That is, we add a 'memory' to each that recalls the sets of targets that have already been seen. Specifically, consider a graph $G = (V, E)$ and k targets $T_1, \dots, T_k \subseteq V$. For all vertex $v \in V$, we denote by $t(x) \subseteq \{1, \dots, k\}$ the set of indexes of target sets to which it belongs: $t(x) := \{i \leq k \mid x \in T_i\}$. Now, we consider the reachability game $G_k = (V_k, E_k)$ with $T \subseteq V$ such that:

- $V_k := V \times 2^{\{1, \dots, k\}}$;
- $E_k := \{((v, s), (v', s')) \mid (v, v') \in E \wedge s' = s \cup t(v)\}$.
- $T := \{(v, \{1, \dots, k\}) \mid v \in V\}$

In this construction, any play from a vertex $v \in V$ can be translated into a play in G_k from $(v, \emptyset) \in V_k$, and reciprocally. It follows that Player A wins in G from v_0 the k -generalized reachability game if and only if she wins from the reachability game G_k from (v_0, \emptyset) . This can be decided in time $O(|G_k|) = O(2^k \cdot |G|) = O(|G|)$ because k is a constant.